

スパースモデリングの電波天文学への展開

— 超解像多次元イメージングから磁場トモグラフィーまで —

秋山 和徳 (Kazu Akiyama)

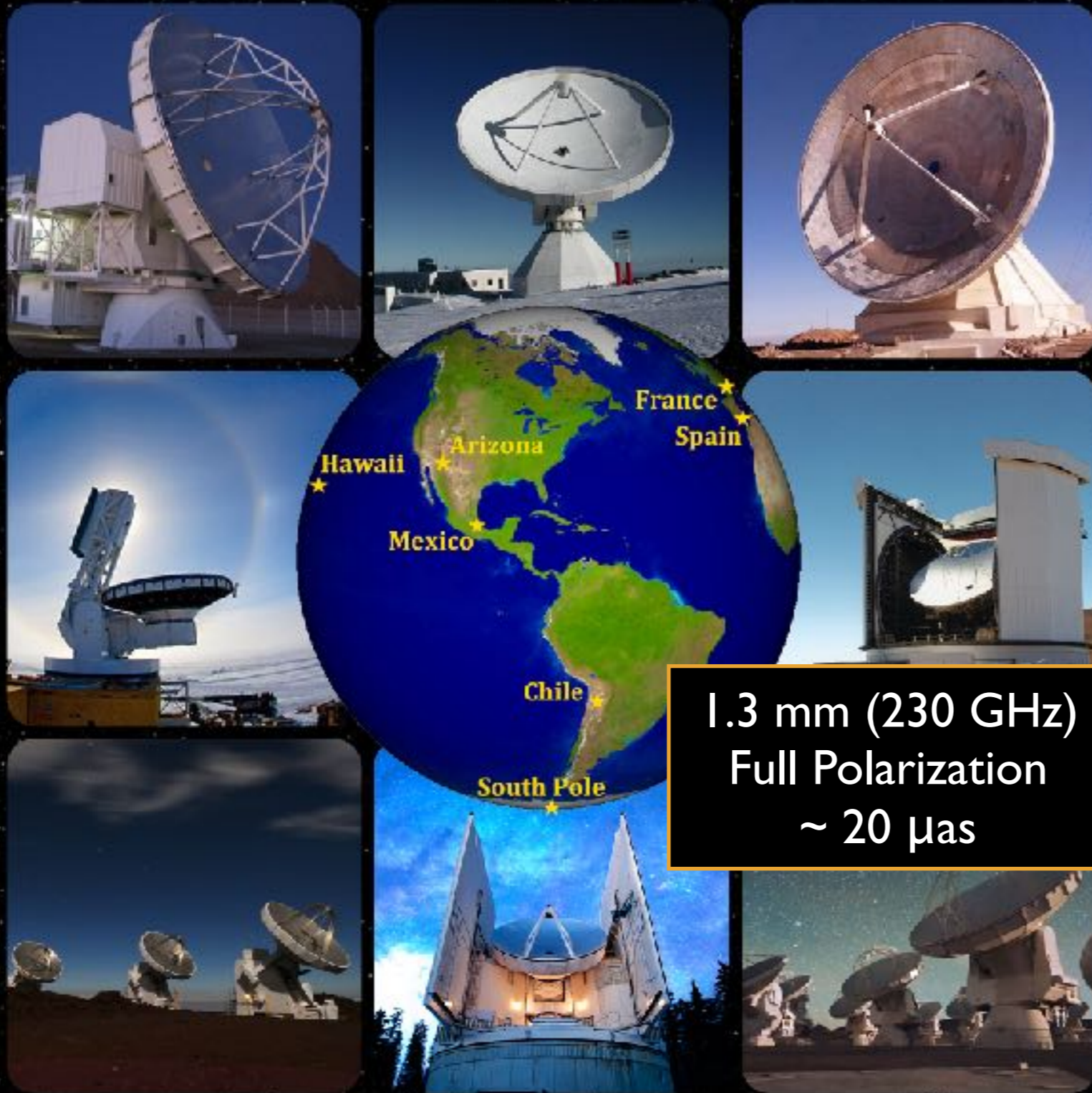
(NRAO Jansky Fellow / MIT Haystack Observatory)



The Event Horizon Telescope Consortium



Black Hole Imaging with the Event Horizon Telescope



Sgr A*



Shiokawa+

M87



Moscibrodka, Dexter+17



Interferometry: Sampling Fourier Components of the Images



Event Horizon Telescope

Interferometry: Sampling Fourier Components of the Images

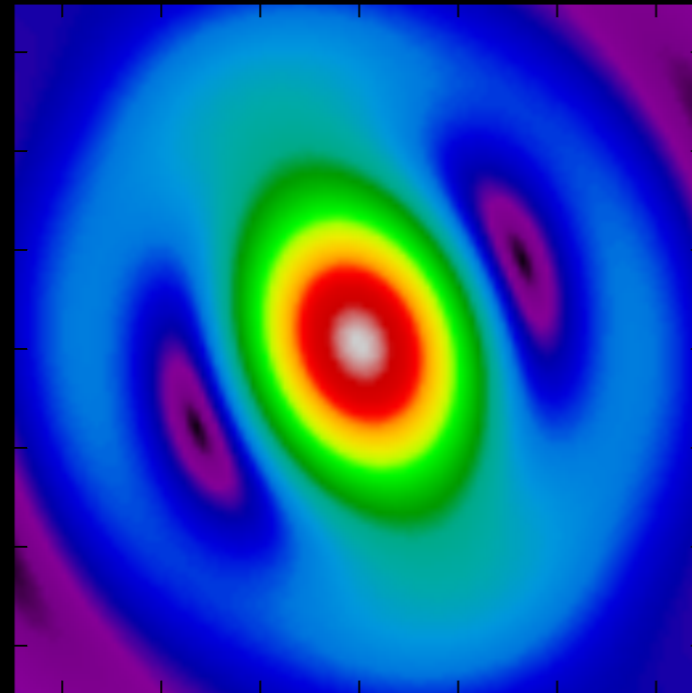
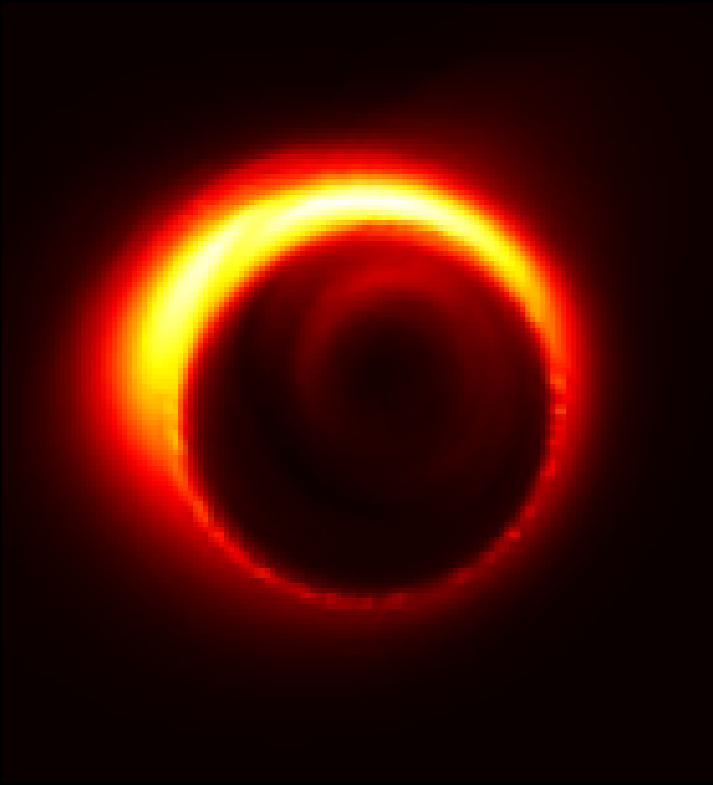
Image



Interferometry: Sampling Fourier Components of the Images

Image

Fourier Domain
(Visibility)

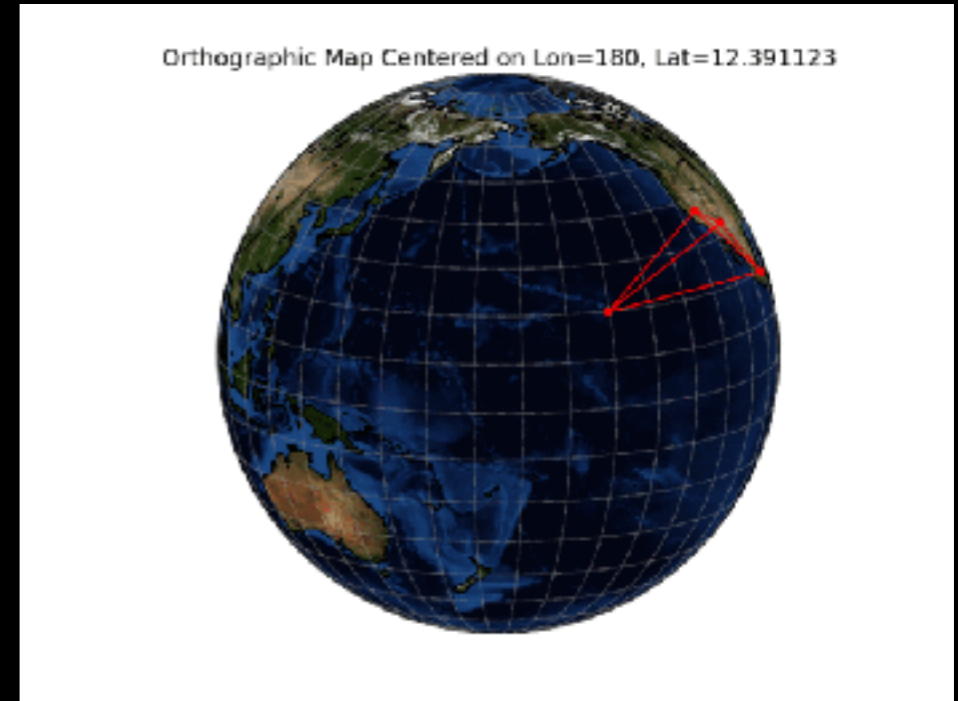
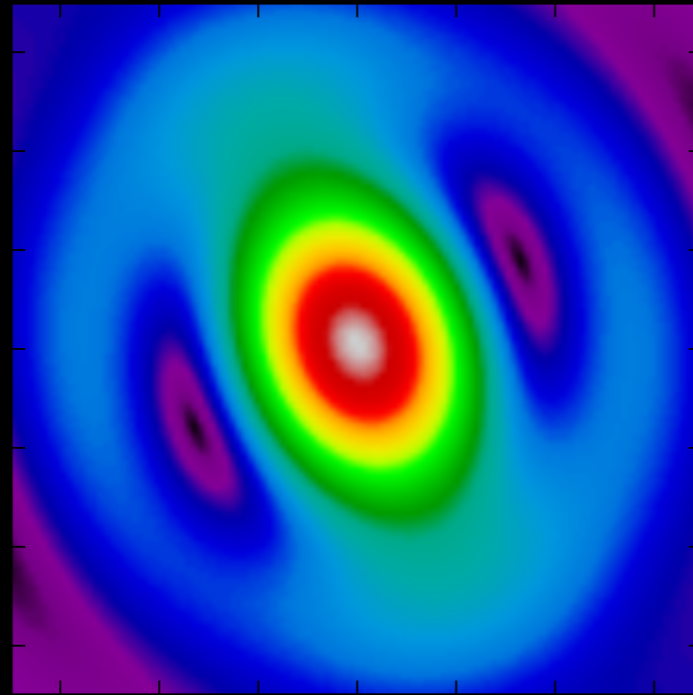
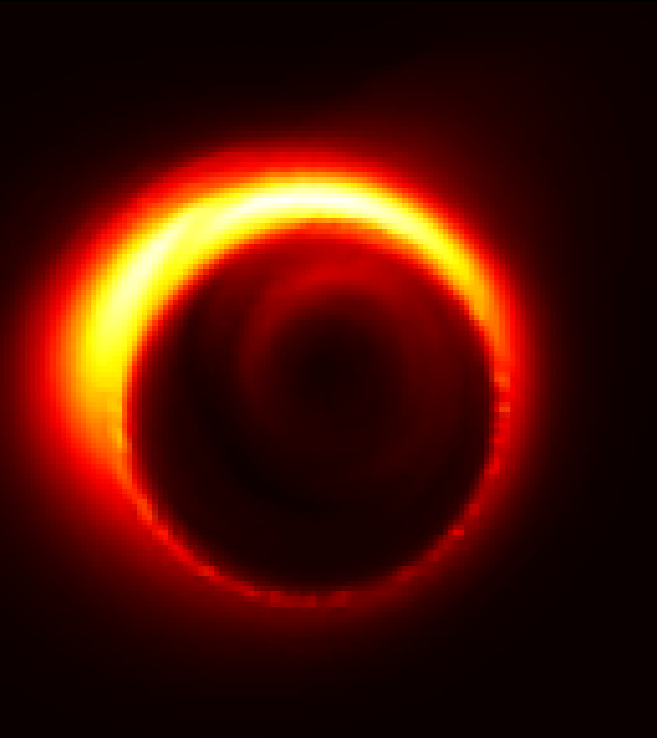


Interferometry: Sampling Fourier Components of the Images

Image

Fourier Domain
(*Visibility*)

Sampling Process
(Projected Baseline = Spatial Frequency)



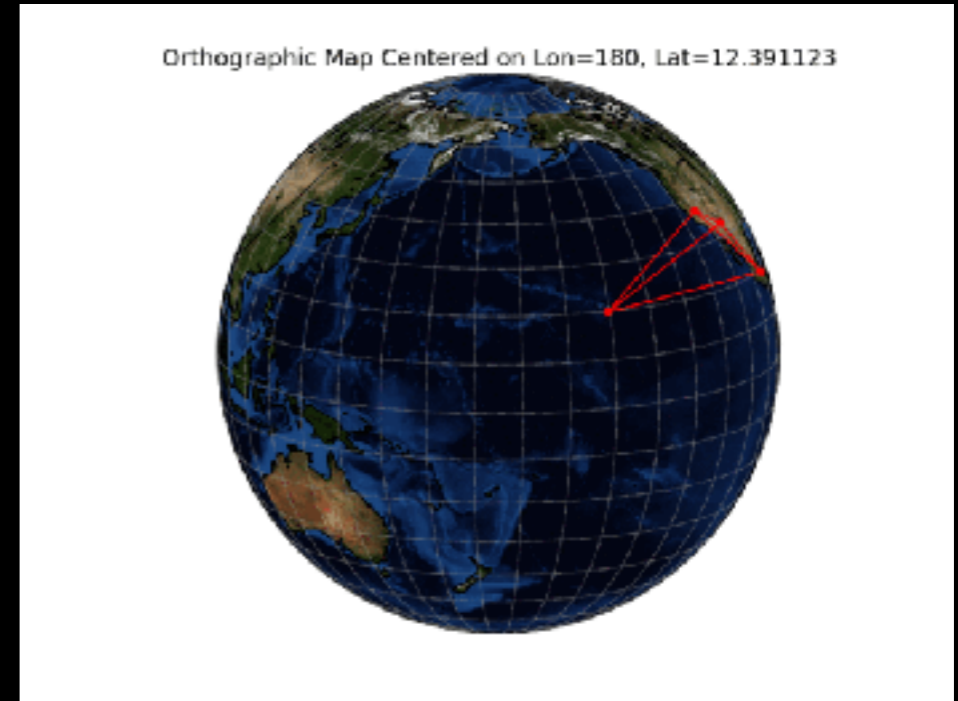
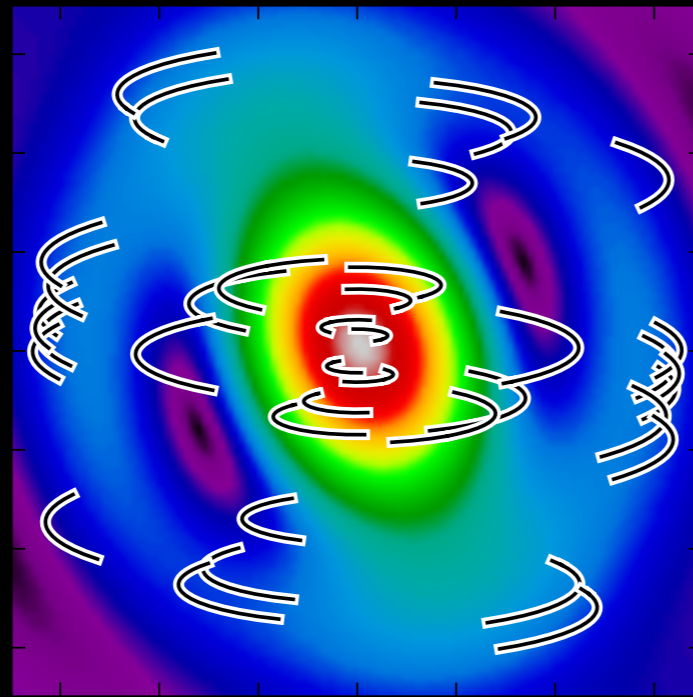
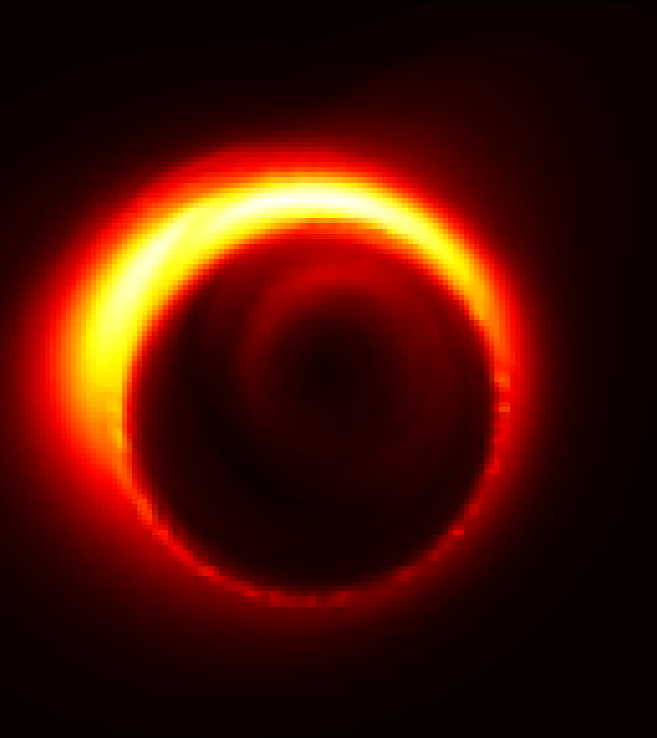
(Images: adapted from [Akiyama et al. 2015, ApJ](#) ; Movie: Laura Vertatschitsch)

Interferometry: Sampling Fourier Components of the Images

Image

**Fourier Domain
(Visibility)**

**Sampling Process
(Projected Baseline = Spatial Frequency)**



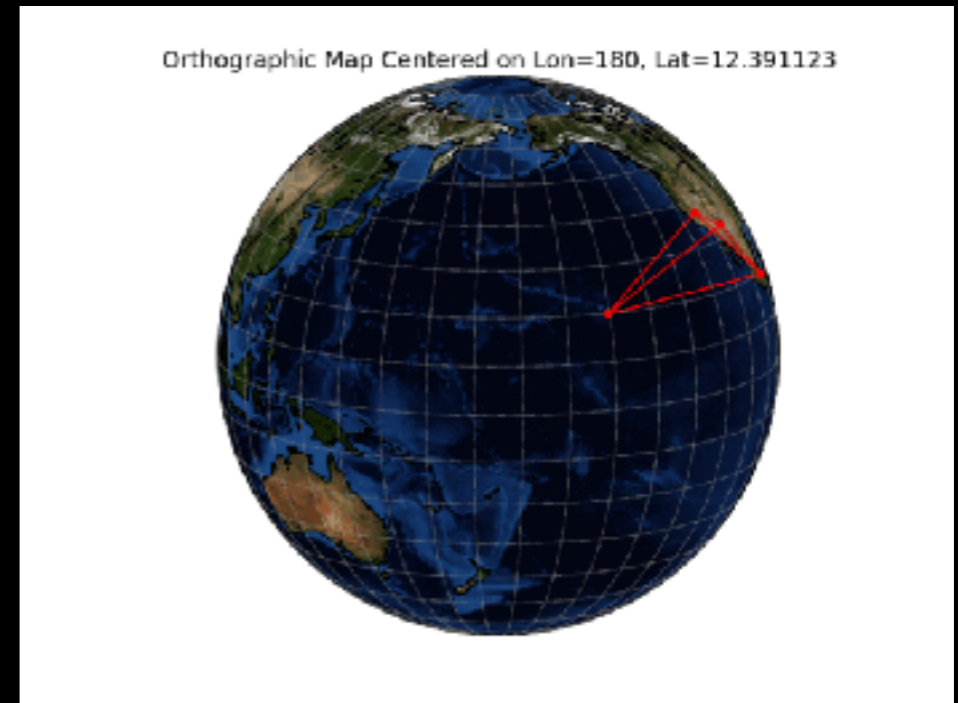
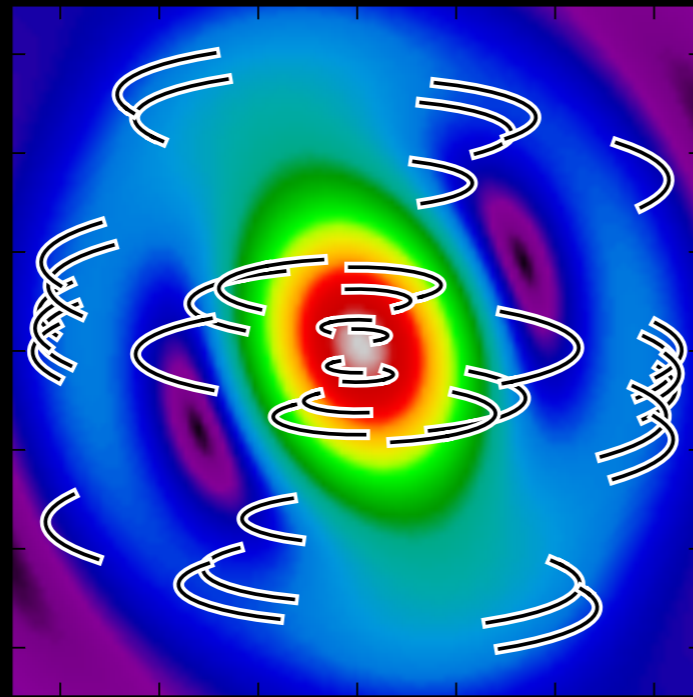
(Images: adapted from [Akiyama et al. 2015, ApJ](#) ; Movie: Laura Vertatschitsch)

Interferometry: Sampling Fourier Components of the Images

Image

Fourier Domain
(*Visibility*)

Sampling Process
(Projected Baseline = Spatial Frequency)



(Images: adapted from [Akiyama et al. 2015, ApJ](#) ; Movie: Laura Vertatschitsch)

Sampling is **NOT** perfect

Interferometric Imaging: Observational equation is *ill-posed*

$$\begin{array}{c}
 \mathbf{V} \\
 \text{(Data)}
 \end{array}
 =
 \begin{array}{c}
 \mathbf{A} \\
 \text{(Fourier Matrix)}
 \end{array}
 \begin{array}{c}
 \mathbf{I} \\
 \text{(Image)}
 \end{array}$$

$$\begin{pmatrix}
 \mathbf{V}_1 \\
 \mathbf{V}_2 \\
 \mathbf{V}_3 \\
 \vdots \\
 \mathbf{V}_M
 \end{pmatrix}
 =
 \begin{pmatrix}
 \exp(i2\pi u_1 x_1) & \exp(i2\pi u_1 x_2) & \dots & \exp(i2\pi u_1 x_N) \\
 \exp(i2\pi u_2 x_1) & \exp(i2\pi u_2 x_2) & \dots & \exp(i2\pi u_2 x_N) \\
 \exp(i2\pi u_3 x_1) & \exp(i2\pi u_3 x_2) & \dots & \exp(i2\pi u_3 x_N) \\
 \vdots & \vdots & \vdots & \vdots \\
 \exp(i2\pi u_M x_1) & \exp(i2\pi u_M x_2) & \dots & \exp(i2\pi u_M x_N)
 \end{pmatrix}
 \begin{pmatrix}
 \mathbf{I}_1 \\
 \mathbf{I}_2 \\
 \mathbf{I}_3 \\
 \vdots \\
 \mathbf{I}_N
 \end{pmatrix}$$

Interferometric Imaging: Observational equation is *ill-posed*

$$\mathbf{V} = \mathbf{A} \mathbf{I}$$

(Data) (Fourier Matrix) (Image)

$$\begin{pmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \\ \mathbf{V}_3 \\ \vdots \\ \mathbf{V}_M \end{pmatrix}$$

$$= \begin{pmatrix} \exp(i2\pi u_1 x_1) & \exp(i2\pi u_1 x_2) & \dots & \exp(i2\pi u_1 x_N) \\ \exp(i2\pi u_2 x_1) & \exp(i2\pi u_2 x_2) & \dots & \exp(i2\pi u_2 x_N) \\ \exp(i2\pi u_3 x_1) & \exp(i2\pi u_3 x_2) & \dots & \exp(i2\pi u_3 x_N) \\ \vdots & \vdots & \vdots & \vdots \\ \exp(i2\pi u_M x_1) & \exp(i2\pi u_M x_2) & \dots & \exp(i2\pi u_M x_N) \end{pmatrix}$$

$$\begin{pmatrix} I_1 \\ I_2 \\ I_3 \\ \vdots \\ I_N \end{pmatrix}$$

- Sampling is NOT perfect

Number of data M < Number of image pixels N

Interferometric Imaging: Observational equation is *ill-posed*

$$\mathbf{V} = \mathbf{A} \mathbf{I}$$

(Data) (Fourier Matrix) (Image)

$$\begin{pmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \\ \mathbf{V}_3 \\ \vdots \\ \mathbf{V}_M \end{pmatrix}$$

$$= \begin{pmatrix} \exp(i2\pi u_1 x_1) & \exp(i2\pi u_1 x_2) & \dots & \exp(i2\pi u_1 x_N) \\ \exp(i2\pi u_2 x_1) & \exp(i2\pi u_2 x_2) & \dots & \exp(i2\pi u_2 x_N) \\ \exp(i2\pi u_3 x_1) & \exp(i2\pi u_3 x_2) & \dots & \exp(i2\pi u_3 x_N) \\ \vdots & \vdots & \vdots & \vdots \\ \exp(i2\pi u_M x_1) & \exp(i2\pi u_M x_2) & \dots & \exp(i2\pi u_M x_N) \end{pmatrix}$$

$$\begin{pmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \\ \mathbf{I}_3 \\ \vdots \\ \mathbf{I}_N \end{pmatrix}$$

- Sampling is NOT perfect
Number of data M < Number of image pixels N
- Equation is *ill-posed*: infinite numbers of solutions
- Interferometric Imaging:
Picking a reasonable solution based on a prior assumption

Sparse Reconstruction: A Popular Approach



Sparse Reconstruction: A Popular Approach

Philosophy: Reconstructing images with the smallest number of point sources within a given residual error



Sparse Reconstruction: A Popular Approach

Philosophy: Reconstructing images with the smallest number of point sources within a given residual error

$$\min_{\mathbf{x}} \|\mathbf{x}\|_0 \text{ subject to } \|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2 < \varepsilon$$



Event Horizon Telescope

Sparse Reconstruction: A Popular Approach

Philosophy: Reconstructing images with the smallest number of point sources within a given residual error

$$\min_{\mathbf{x}} \|\mathbf{x}\|_0 \text{ subject to } \|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2 < \varepsilon$$

L_p -norm:

$$\|\mathbf{x}\|_p = \left(\sum_i |x_i|^p \right)^{\frac{1}{p}} \quad (p > 0)$$

$\|\mathbf{x}\|_0$ = number of non-zero pixels in the image



Sparse Reconstruction: A Popular Approach

Philosophy: Reconstructing images with the smallest number of point sources within a given residual error

$$\min_{\mathbf{x}} \|\mathbf{x}\|_0 \text{ subject to } \|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2 < \varepsilon$$

*Number
of non-zero pixels
(point sources)*

L_p -norm:

$$\|\mathbf{x}\|_p = \left(\sum_i |x_i|^p \right)^{\frac{1}{p}} \quad (p > 0)$$

$\|\mathbf{x}\|_0$ = number of non-zero pixels in the image



Sparse Reconstruction: A Popular Approach

Philosophy: Reconstructing images with the smallest number of point sources within a given residual error

$$\min_{\mathbf{x}} \|\mathbf{x}\|_0 \text{ subject to } \|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2 < \varepsilon$$

Number
of non-zero pixels
(point sources)

Data Obs.
Matrix Image

Chi-square: Consistency
between data and the image

L_p -norm:

$$\|\mathbf{x}\|_p = \left(\sum_i |x_i|^p \right)^{\frac{1}{p}} \quad (p > 0)$$

$\|\mathbf{x}\|_0$ = number of non-zero pixels in the image



Event Horizon Telescope

Sparse Reconstruction: A Popular Approach

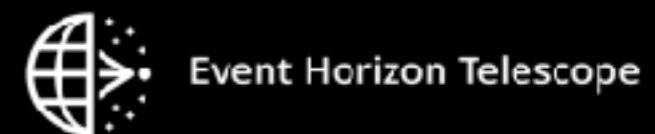
Philosophy: Reconstructing images with the smallest number of point sources within a given residual error

$$\min \|x\|_0 \text{ subject to } \|y - Ax\|_2^2 < \varepsilon$$

Computationally very expensive!!
(It can be solved for $N < \sim 100$)

- L_0 norm is not continuous, nondifferentiable
- Combinational Optimization

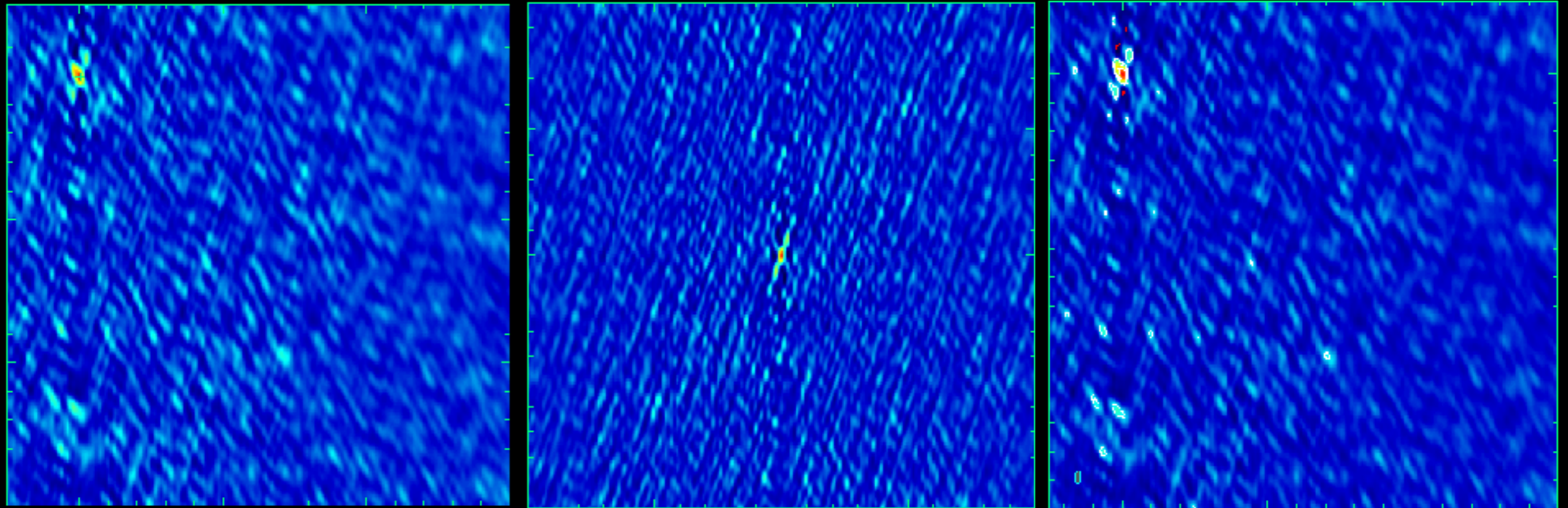
$\|x\|_0$ = number of non-zero pixels in the image



Sparse Reconstruction: CLEAN (greedy approach)

CLEAN (Hobgorn 1974) = Matching Pursuit (Mallet & Zhang 1993)

Computationally very cheap, but highly affected by the Point Spread Function



Dirty map:
FT of zero-filled
Visibility

Point Spread Function:
Dirty map
for the point source

Solution:
Point sources
+ Residual Map

(3C 273, VLBA-MOJAVE data at 15 GHz)



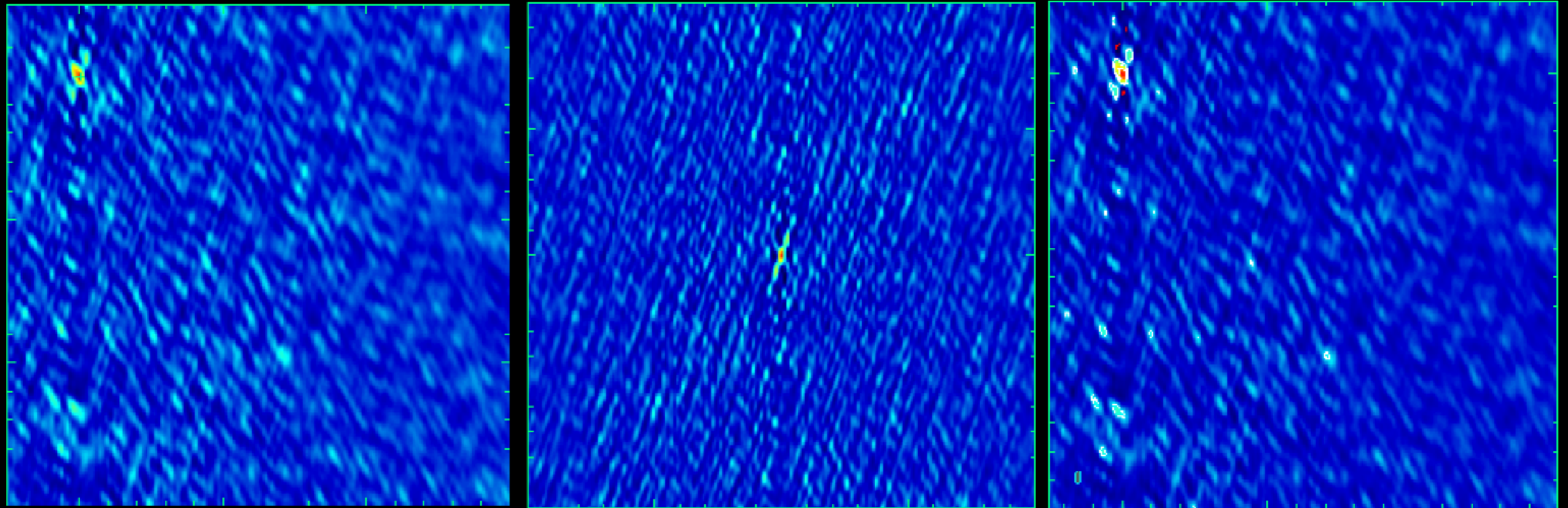
Event Horizon Telescope



Sparse Reconstruction: CLEAN (greedy approach)

CLEAN (Hobgorn 1974) = Matching Pursuit (Mallet & Zhang 1993)

Computationally very cheap, but highly affected by the Point Spread Function



Dirty map:
FT of zero-filled
Visibility

Point Spread Function:
Dirty map
for the point source

Solution:
Point sources
+ Residual Map

(3C 273, VLBA-MOJAVE data at 15 GHz)



Event Horizon Telescope

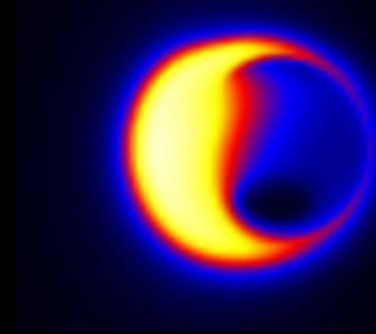
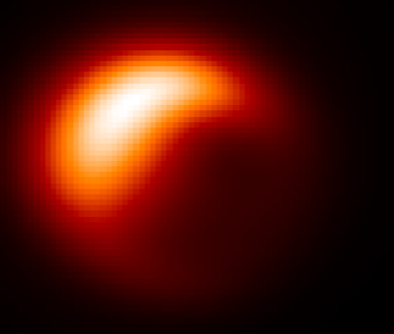


Sparse Reconstruction: CLEAN (greedy approach)

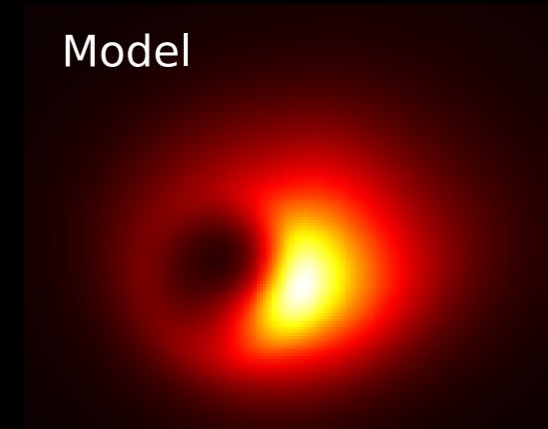
CLEAN (Hobgorn 1974) = Matching Pursuit (Mallet & Zhang 1993)

CLEAN is problematic for the black hole shadows?

Ground
Truth



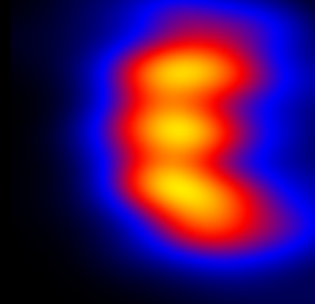
Model



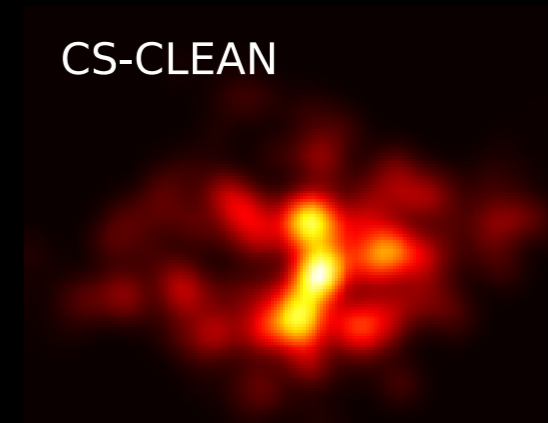
CLEAN



CLEAN



CS-CLEAN



Fabian Baron,
EHT 2012

Chael+2016 ApJ

Akiyama+2017a, ApJ
Akiyama+2017b, AJ



Event Horizon Telescope

Sparse Reconstruction: L1 Regularization

LASSO (Tibshirani 1996)



Event Horizon Telescope

Sparse Reconstruction: L1 Regularization

LASSO (Tibshirani 1996)

Convex Relaxation: Relaxing L0-norm to a convex, continuous, and differentiable function



Event Horizon Telescope

Sparse Reconstruction: L1 Regularization

LASSO (Tibshirani 1996)

Convex Relaxation: Relaxing L0-norm to a convex, continuous, and differentiable function

$$\min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{subject to} \quad \|\mathbf{y} - \mathbf{Ax}\|_2^2 < \varepsilon$$



Event Horizon Telescope

Sparse Reconstruction: L1 Regularization

LASSO (Tibishirani 1996)

Convex Relaxation: Relaxing L0-norm to a convex, continuous, and differentiable function

$$\min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{subject to} \quad \|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2 < \varepsilon$$



equivalent

$$\min_{\mathbf{x}} \left(\underbrace{\|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2}_{\text{Chi-square}} + \underbrace{\Lambda_l \|\mathbf{x}\|_1}_{\text{Regularization on sparsity}} \right).$$

Chi-square

Regularization
on *sparsity*



Event Horizon Telescope

Sparse Reconstruction: L1 Regularization

LASSO (Tibishirani 1996)

Convex Relaxation: Relaxing L0-norm to a convex, continuous, and differentiable function

$$\min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{subject to} \quad \|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2 < \varepsilon$$



equivalent

$$\min_{\mathbf{x}} \left(\underbrace{\|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2}_{\text{Chi-square}} + \underbrace{\Lambda_l \|\mathbf{x}\|_1}_{\text{Regularization on sparsity}} \right).$$

Chi-square

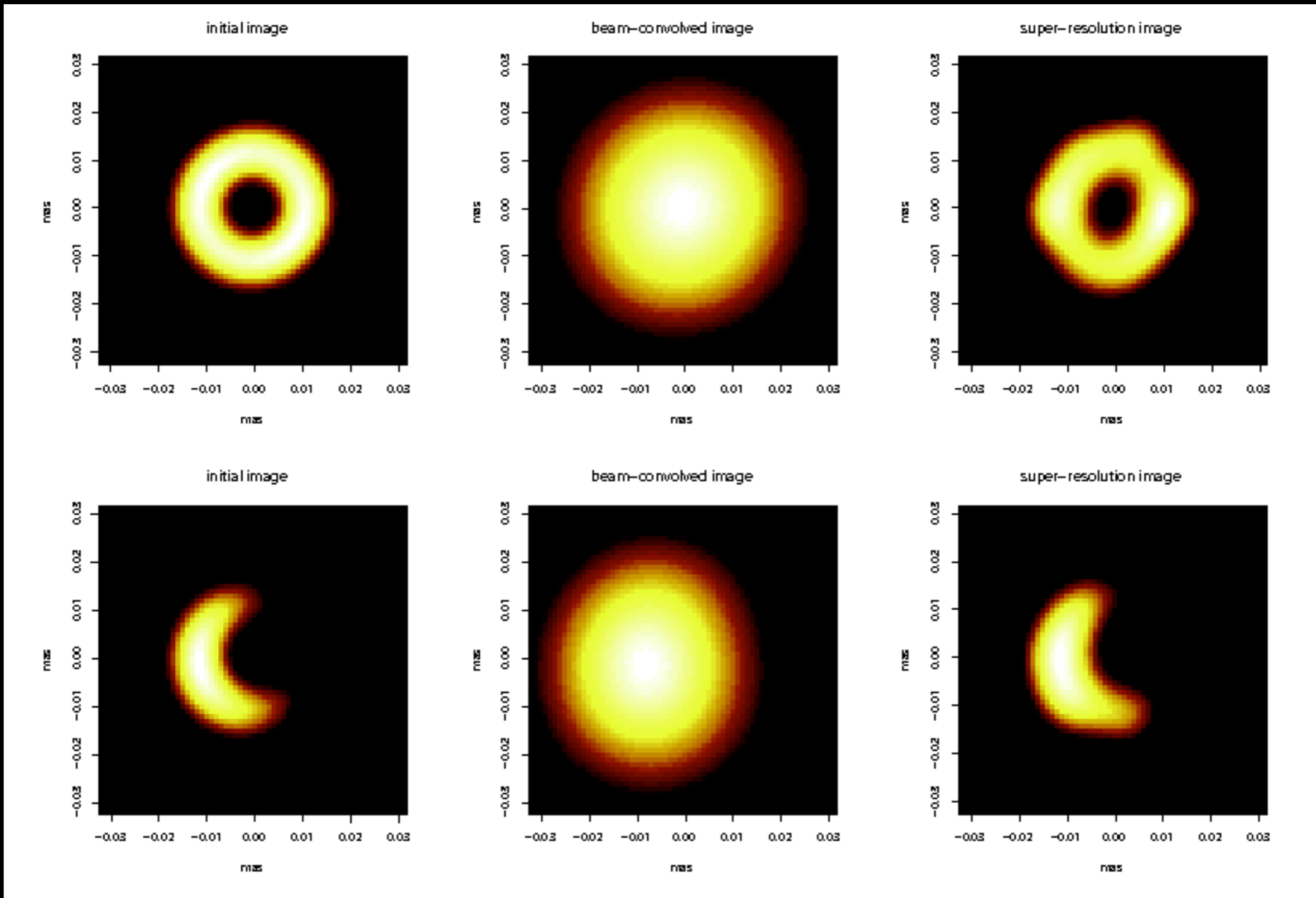
Regularization
on *sparsity*

- Reconstruction purely in the visibility domain:
 - Not affected by de-convolution beam (point spread function)
- Many applications after appearance of *Compressed Sensing* (Donoho, Candes+)

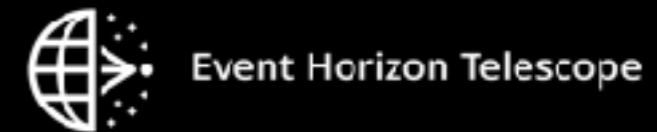


Event Horizon Telescope

Sparse Reconstruction: L1 Regularization LASSO (Tibishirani 1996)

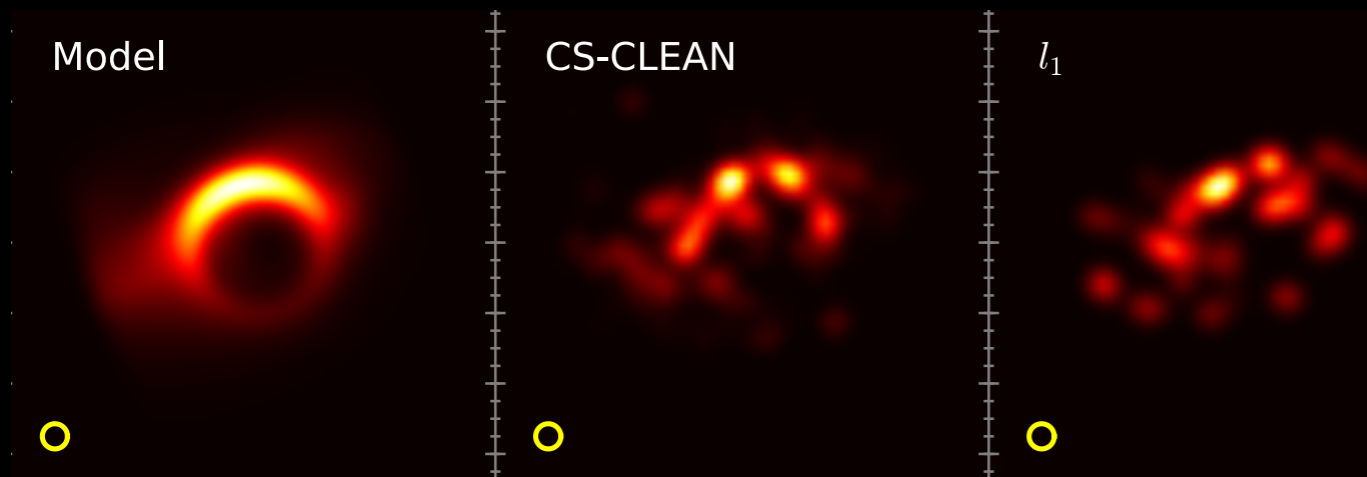


(Honma, *Akiyama*, Uemura & Ikeda 2014, PASJ)



Pursuing only sparsity is not optimal

A key assumption in CLEAN and L1 regularization: images must be sparse.



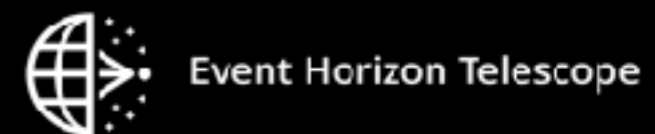
May NOT work!

- Extended source
- Even compact source with too small image pixels

Akiyama et al. 2017b, AJ



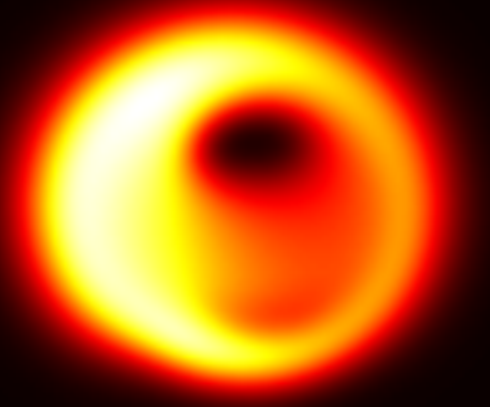
We need somewhat sparse and smooth images
NOT depending on adopted sizes of imaging pixels.



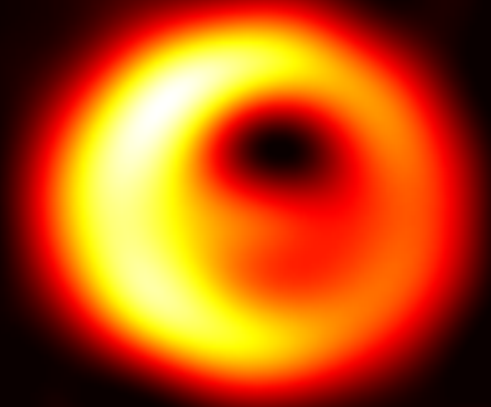
Sparse Modeling on the Gradient Image

$$\min_{\mathbf{x}} \left(\|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2 + \Lambda_l \|\mathbf{x}\|_1 + \Lambda_t \|\mathbf{x}\|_{tv} \right)$$

Model



mfista (L1+TV²)

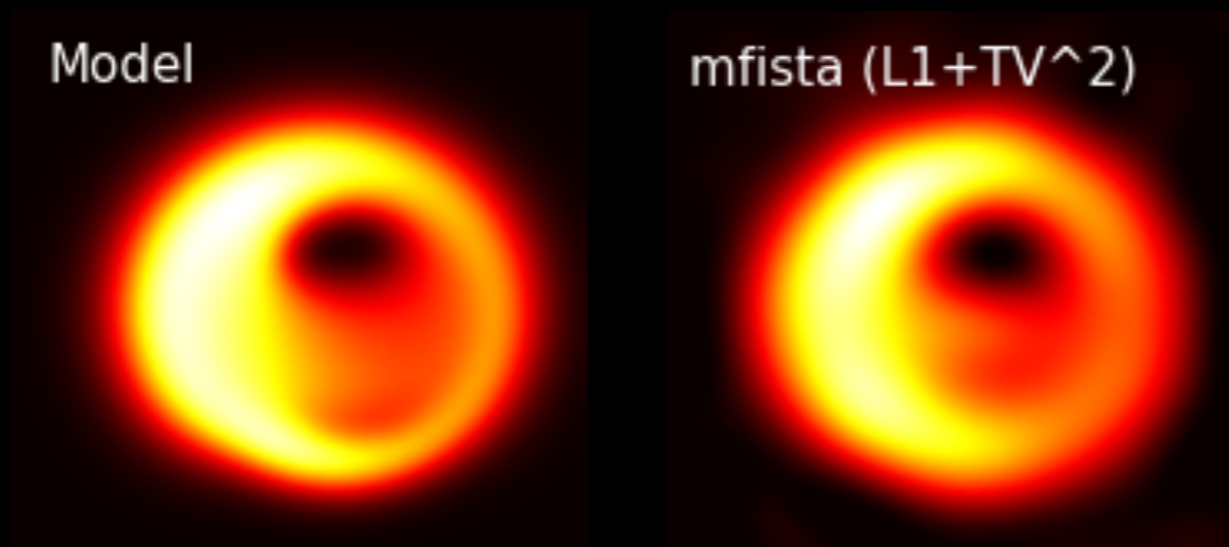


Kuramochi & *KA* et al. 2018
ApJ, in press

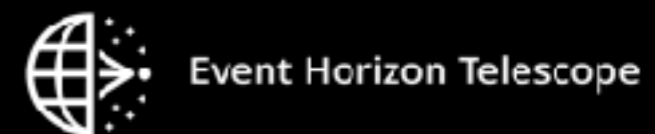
Sparse Modeling on the Gradient Image

$$\min_{\mathbf{x}} \left(\underbrace{\| \mathbf{y} - \mathbf{A}\mathbf{x} \|^2_2}_{\text{Chisquare}} + \Lambda_l \| \mathbf{x} \|_1 + \Lambda_t \| \mathbf{x} \|_{tv} \right)$$

Chisquare



Kuramochi & *KA* et al. 2018
ApJ, in press



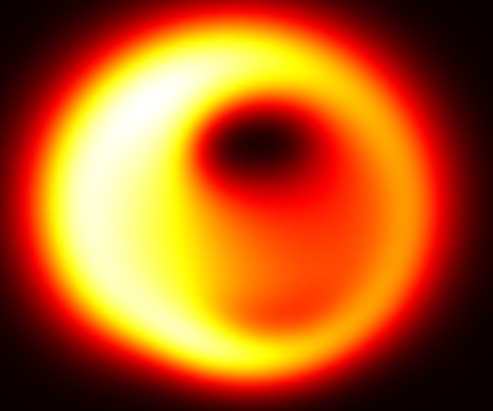
Sparse Modeling on the Gradient Image

$$\min_{\mathbf{x}} \left(\underbrace{\| \mathbf{y} - \mathbf{A}\mathbf{x} \|^2_2}_{\text{Chisquare}} + \underbrace{\Lambda_l \| \mathbf{x} \|_1}_{\text{L1 norm}} + \Lambda_t \| \mathbf{x} \|_{tv} \right)$$

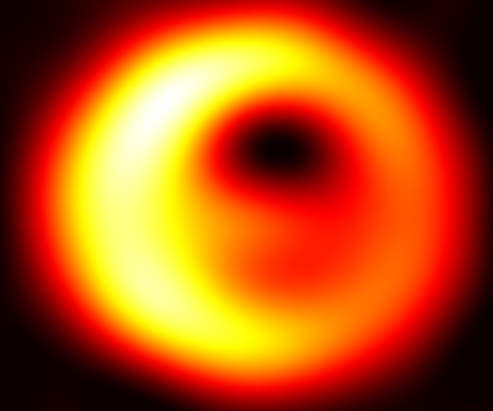
Chisquare

L1 norm

Model



mfista (L1+TV^2)



Kuramochi & *KA* et al. 2018
ApJ, in press

Sparse Modeling on the Gradient Image

$$\min_{\mathbf{x}} \left(\underbrace{\|y - \mathbf{A}\mathbf{x}\|_2^2}_{\text{Chisquare}} + \underbrace{\Lambda_l \|\mathbf{x}\|_1}_{\text{L1 norm}} + \underbrace{\Lambda_t \|\mathbf{x}\|_{TV}}_{\text{Total Variation:}} \right)$$

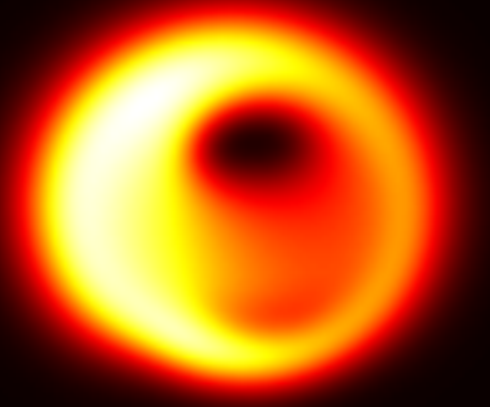
Chisquare

L1 norm

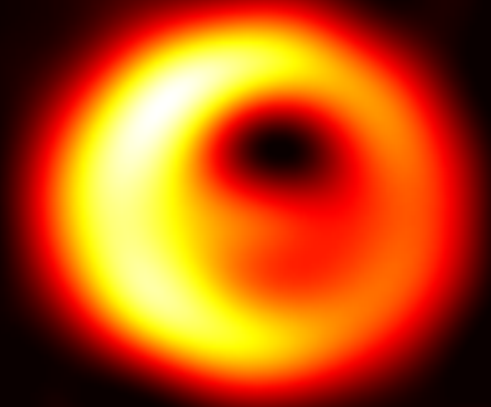
Total Variation:

Regularizing the *sparsity on the gradient domain*
= Favoring smooth images

Model



mfista (L1+TV^2)



Kuramochi & *KA* et al. 2018
ApJ, in press

Sparse Modeling on the Gradient Image

$$\min_{\mathbf{x}} \left(\underbrace{\|y - \mathbf{A}\mathbf{x}\|_2^2}_{\text{Chisquare}} + \underbrace{\Lambda_l \|\mathbf{x}\|_1}_{\text{L1 norm}} + \underbrace{\Lambda_t \|\mathbf{x}\|_{\text{tv}}}_{\text{Total Variation:}} \right)$$

Chisquare

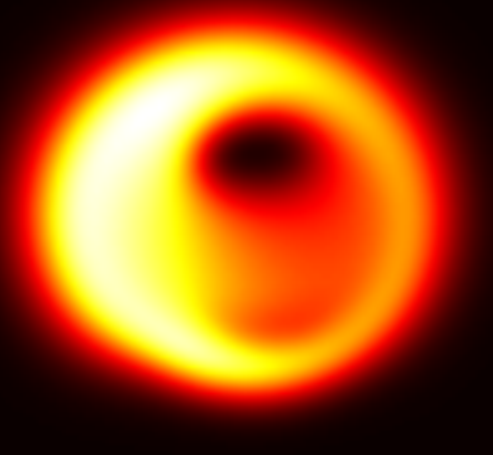
L1 norm

Total Variation:

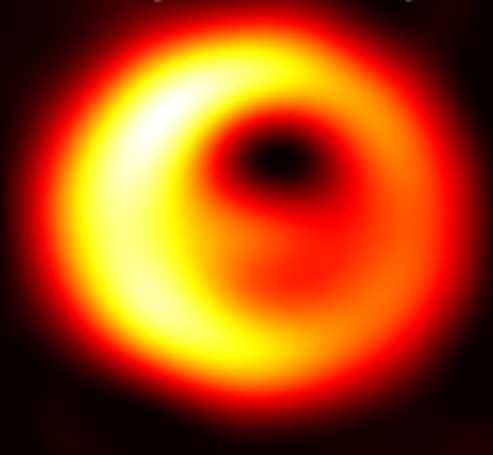
Regularizing the *sparsity on the gradient domain*
= Favoring smooth images

$$\|\mathbf{x}\|_{\text{tv}} = \sum_i \sum_j \left(|x_{i+1,j} - x_{i,j}|^2 + |x_{i,j+1} - x_{i,j}|^2 \right).$$

Model



mfista (L1+TV^2)



Kuramochi & KA et al. 2018
ApJ, in press

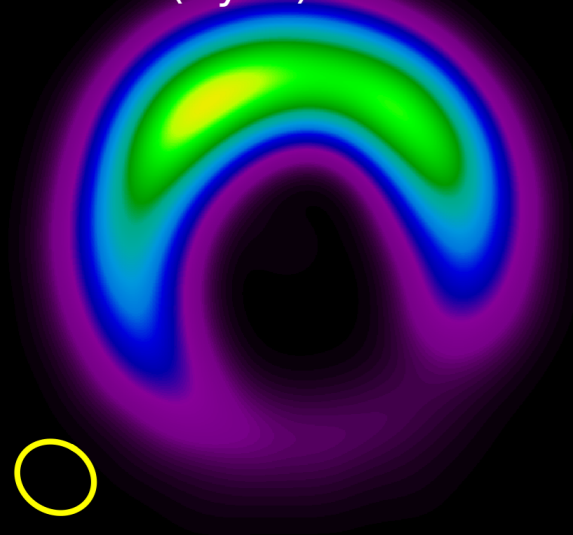
Application to Real Data: Protoplanetary Disks

ALMA Observations of Protoplanetary Disk HD 142527 (345 GHz)

Compact configuration

Nominal
Resolution

CLEAN (Cyc3)

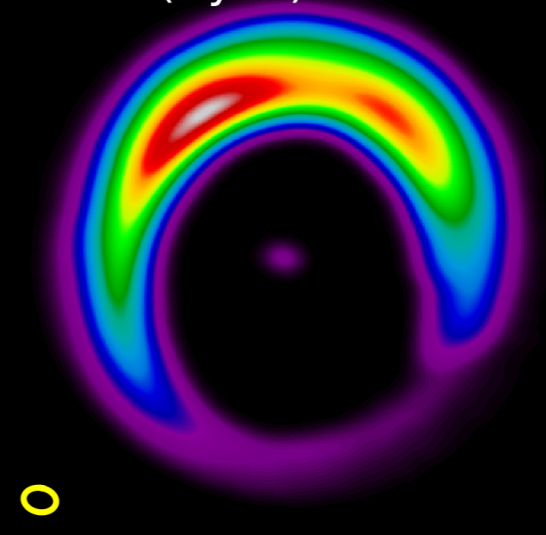


Kataoka et al. 2016, ApJ

Intermediate config.

Nominal
Resolution

CLEAN (Cyc2)



Fukagawa et al. in prep.



Event Horizon Telescope

Application to Real Data: Protoplanetary Disks

ALMA Observations of Protoplanetary Disk HD 142527 (345 GHz)

Compact configuration

Intermediate config.

Nominal Resolution

Superresolution
(same to the intermediate configuration)

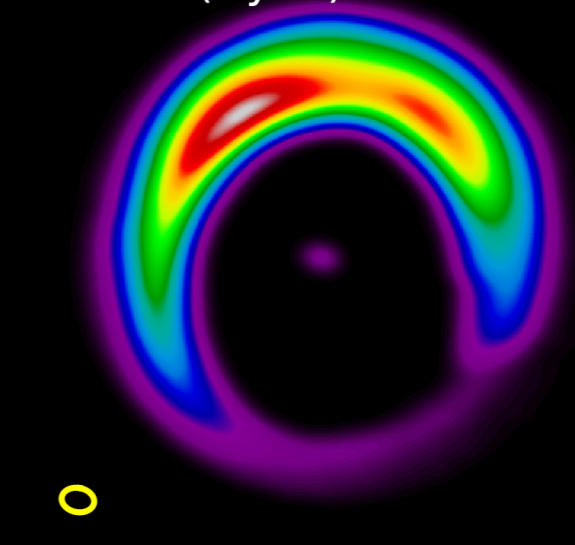
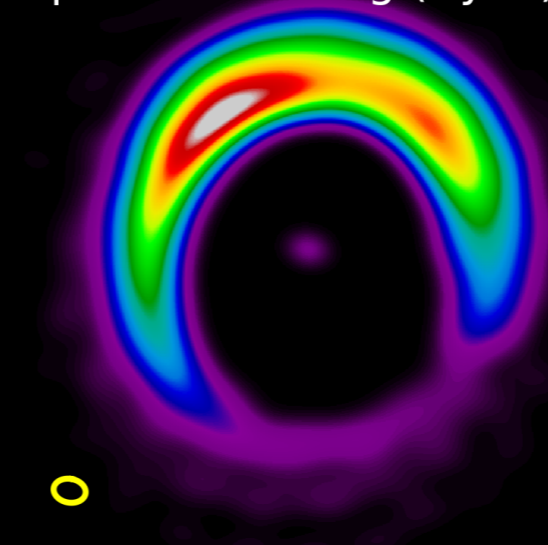
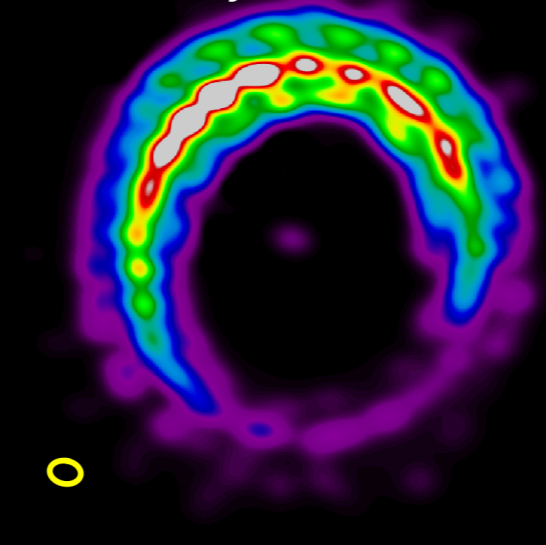
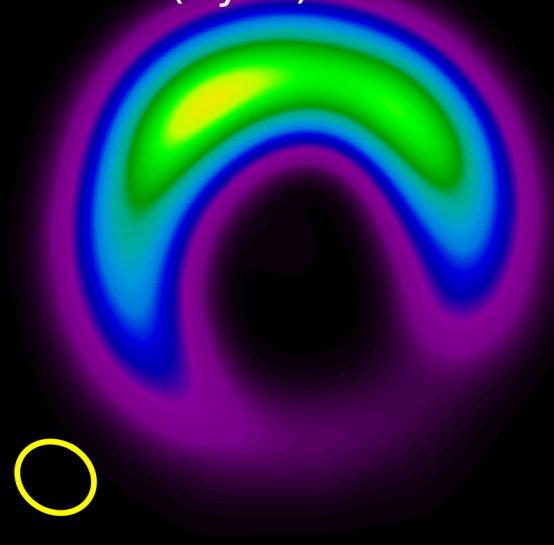
Nominal Resolution

CLEAN (Cyc3)

CLEAN (Cyc3)

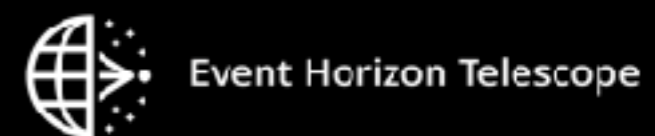
Sparse Modeling (Cyc3)

CLEAN (Cyc2)

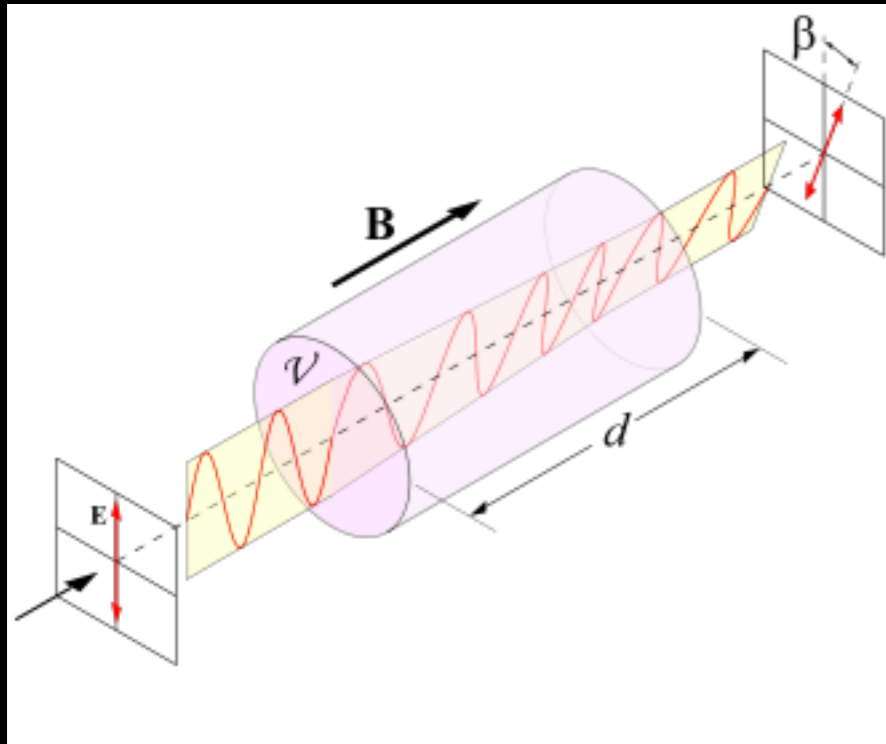


Kataoka et al. 2016, ApJ

Fukagawa et al. in prep.
(Yamaguchi, KA, & Kataoka et al. in prep.)



Applications to SKA Science: Faraday Tomography



EVPA rotation of radio waves in magnetized plasma

$$\chi = \chi_0 + RM\lambda^2$$

$$RM \text{ (rad m}^{-2}\text{)} \approx 811.9 \int \left(\frac{n_e}{\text{cm}^{-2}} \right) \left(\frac{B_{\parallel}}{\mu\text{G}} \right) \left(\frac{dr}{\text{kpc}} \right)$$

Rotation angle is proportional to λ^2
 = phase rotation in linear Pol spectrum

This is very similar to what we usually see in interferometric data.

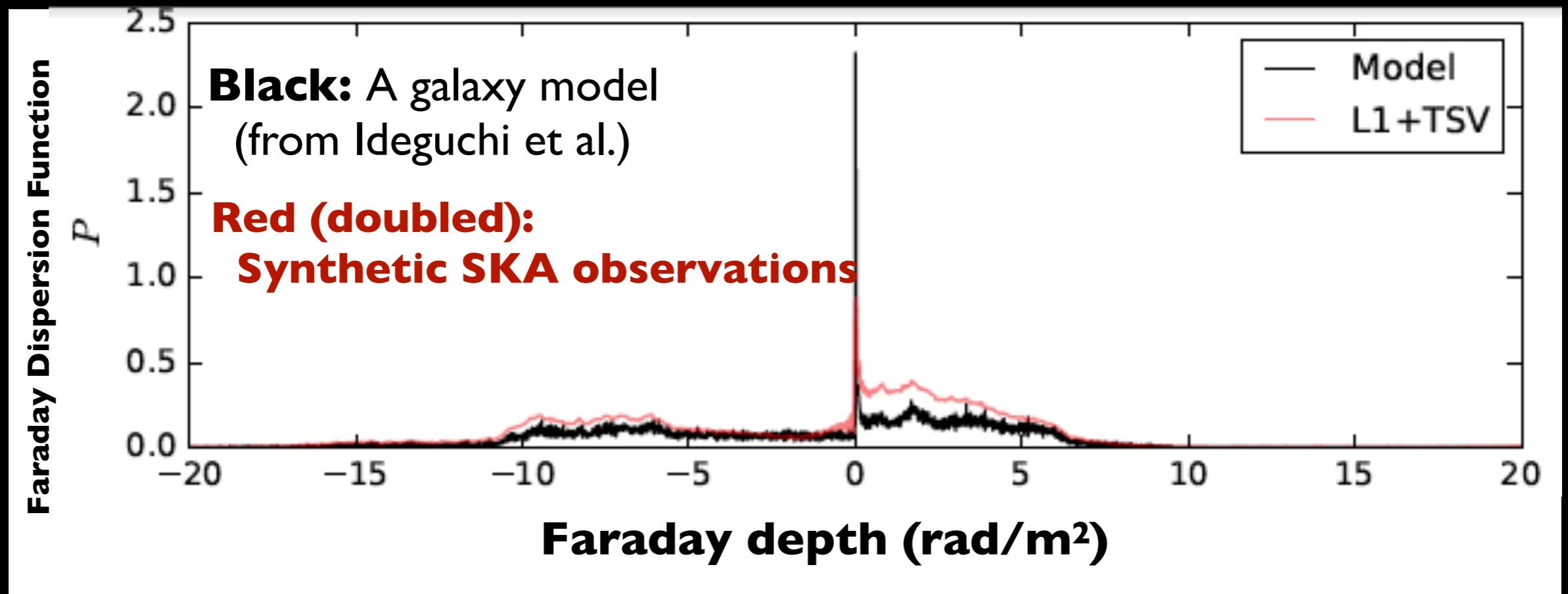
(e.g.) A point source in the image causes a phase rotation in the visibility, which is a spatial spectrum of the image.

$$\Delta\varphi = 2\pi\chi_0 u \quad \text{for a point source at } x = x_0$$

(x, u) for interferometric imaging; (RM, λ^2) for Faraday Rotation

Applications to SKA Science: Faraday Tomography

$$\begin{array}{ccc} \mathbf{Y} & = & \mathbf{A} \mathbf{X} \\ \text{Linear} & & \text{Fourier} & & \text{Fourier} \\ \text{Polarization} & & \text{Transform} & & \text{Dispersion} \\ \text{Spectra} & & \text{for Faraday depth} & & \text{Function} \end{array}$$



(Akiyama et al. in prep., Collaboration with SKA-JP Faraday Tomography WG)

EHT Imaging: Fusion of Young Powers & Divergence

Simulation

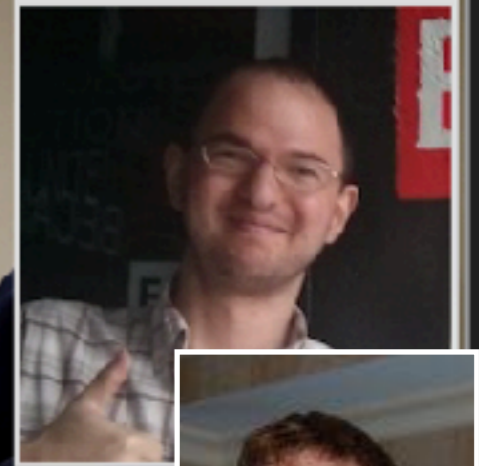
Andre Young
(SAO Astronomy)

Kazu Akiyama
(MIT Astronomy)

Julian Rosen
(UGA Mathematics)

Lindy Blackburn
(SAO Astronomy)

Katie Bouman
(MIT Computer Vision)



Michael Johnson
(SAO Astronomy)

Andrew Chael
(Harvard Physics)

Simulation

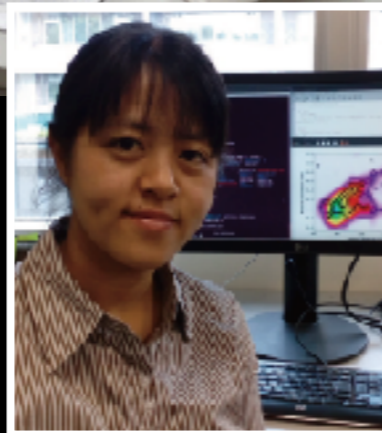
- An or
- Earth



Marki Honma
NAOJ
Astronomy



Shiro Ikeda
ISM Statistical
Mathematics



Fumie Tazaki
NAOJ Astronomy



Kazuki Kuramochi
U.Tokyo Astronomy



Challenges for VLBI Imaging



Challenges for VLBI Imaging



No good phase calibrators!

We need to carefully CLEAN
so that images are reasonably smooth and
sparse, and consistent with closure phases.



Event Horizon Telescope

Challenges for VLBI Imaging

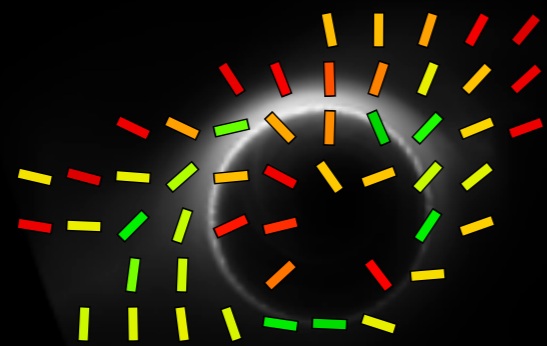


No good phase calibrators!

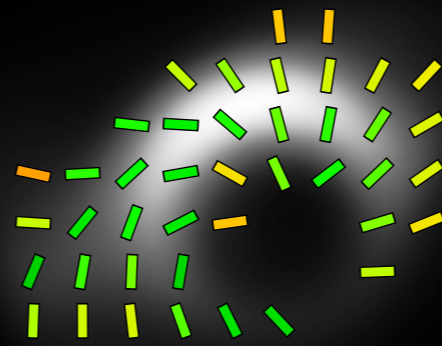
We need to carefully CLEAN so that images are reasonably smooth and sparse, and consistent with closure phases.

Solution: Imaging from Amplitudes + Closure Phases

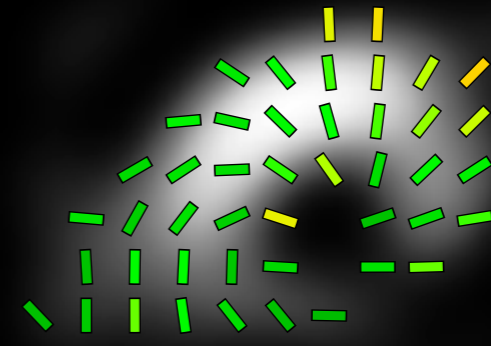
Model



Model (Convolved)



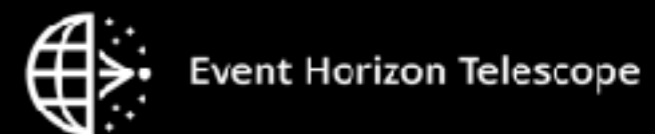
EHT 2017



Sparse Modeling: *Akiyama* et al. 2017a, Kuramochi & *KA* et al. 2018

MEM: Lu et al. 2014, 2016, Fish et al. 2016, Chael et al. 2016

CHIRP: Bouman et al. 2016



Challenges for VLBI Imaging

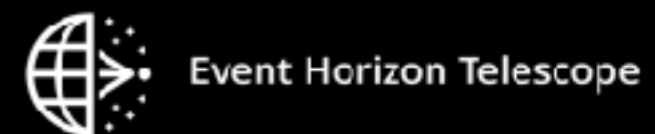


Event Horizon Telescope

Challenges for VLBI Imaging



No good amplitude calibrations!
We need to carefully CLEAN
so that images are consistent with
amplitude gains of $\sim 10\text{-}30\%$, etc. . . .

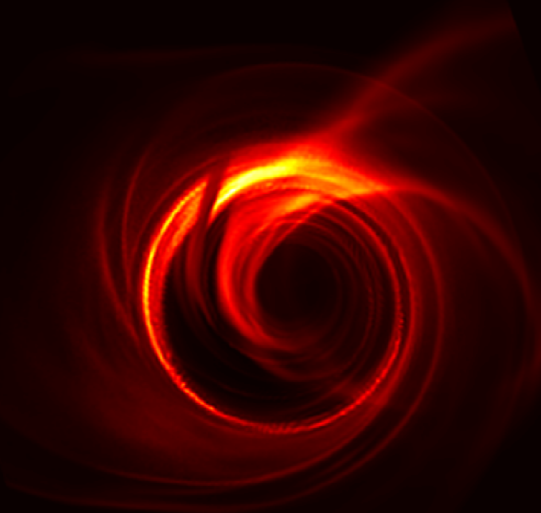


Challenges for VLBI Imaging

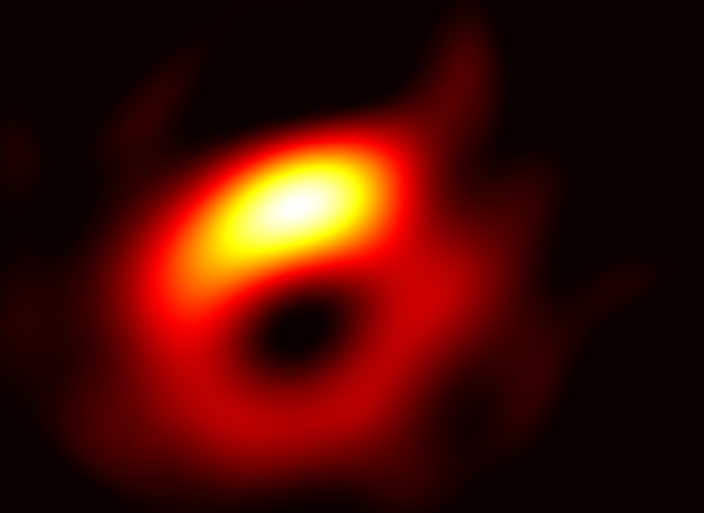


No good amplitude calibrations!
We need to carefully CLEAN
so that images are consistent with
amplitude gains of $\sim 10\text{-}30\%$, etc. . . .

Solution: Full Closure Imaging (Cl.Amplitudes + Cl. Phase)



M87 Jet Model
(Moscibrodzka+17)



EHT 2017/2018
Full Closure Imaging (Sparse Modeling)

Theoretical Background: Chael , . . . , [KA](#) et al. 2018, ApJ, in press.

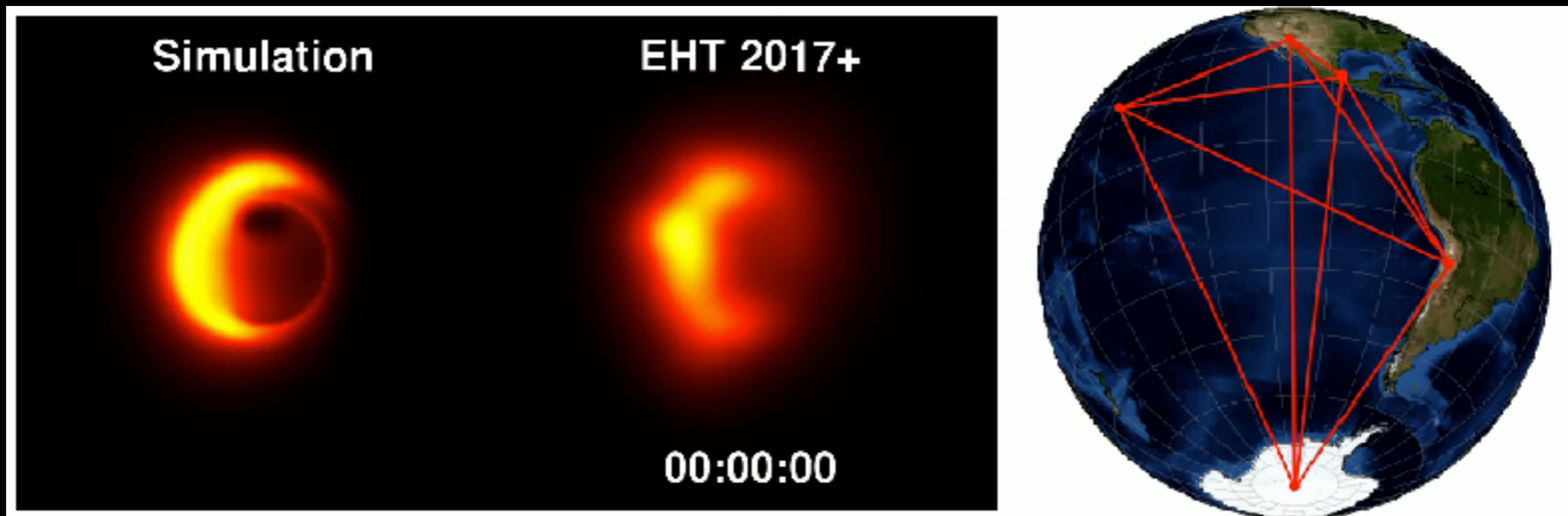


Challenges for VLBI Imaging



Sgr A* (and M87) has a time variability.

Solution: regularize and solve movies.
(extension of sparse and other regularizers in time direction)



(Johnson ,..., [KA](#) et al. 2017, ApJ, Bouman et al. 2017, submitted)



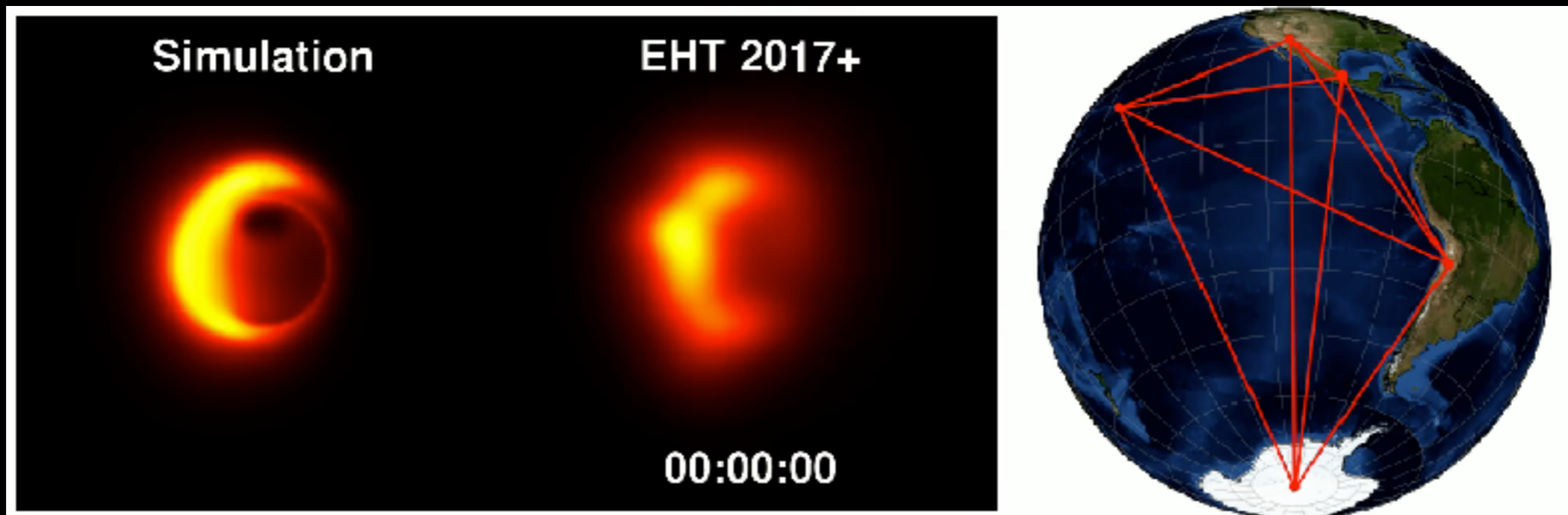
Event Horizon Telescope

Challenges for VLBI Imaging

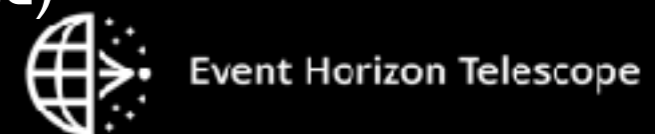


Sgr A* (and M87) has a time variability.

Solution: regularize and solve movies.
(extension of sparse and other regularizers in time direction)



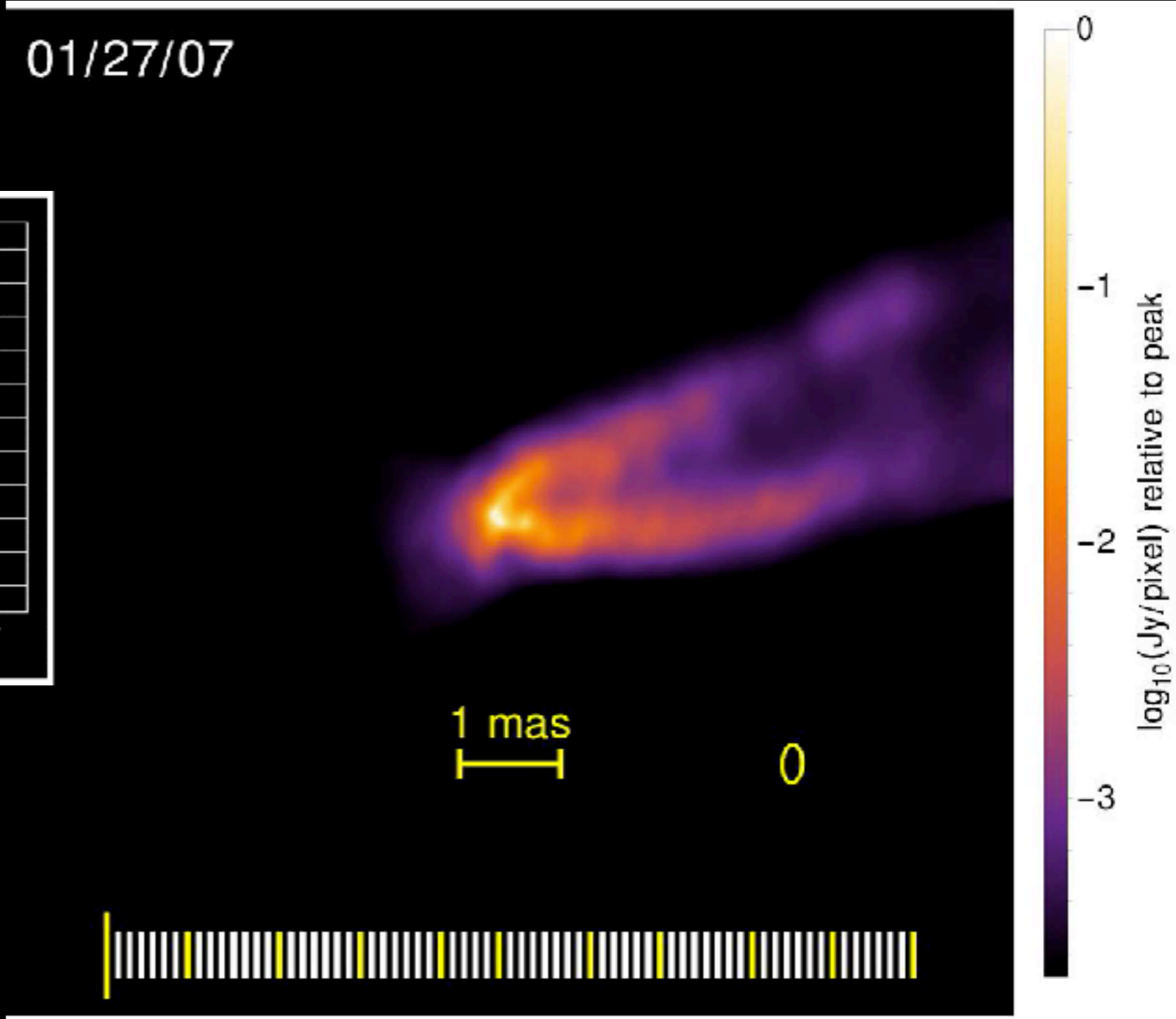
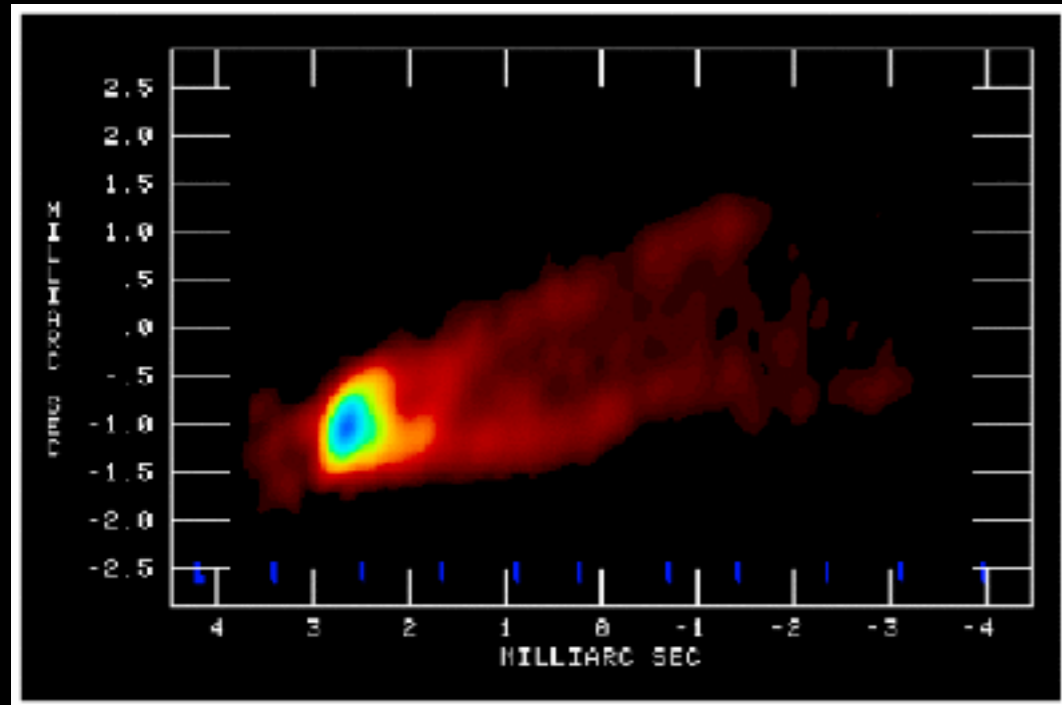
(Johnson ,..., [KA](#) et al. 2017, ApJ, Bouman et al. 2017, submitted)



Applications of Dynamical Imaging to M87 data

Revision of the Walker+08 movie

01/27/07



(Johnson, ..., *KA* et al. 2017, ApJ)



Implementation for the Next Generation Interferometers

VLBI, Optical interferometers (EHT, VLBA, EVN, EAVN, Radio Astron...)

- Absolute phase information will be lost in general
- Amplitude calibration could be not reliable
- Require closure imaging and self-calibration

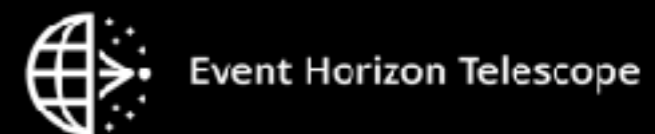
Python-interfaced package **SMILI** (Akiyama et al. 2018, to be submitted)

Present & next generation connected interferometers

(ALMA, VLA, SKA, ngVLA, LOFAR, ...)

- Should be integrated into 3rd generation calibration packages handling direction-dependent effects (see, e.g., Smirnov 2011, A&A)
- Full complex visibility imaging & selfcal would be enough.

Implementation to **CASA** (Nakazato, Ikeda, KA, Kosugi, in prep.)



Summary

- Sparse Modeling (and other EHT imaging techniques) provide a new opportunity to obtain high-quality, high-resolution images (and movies) from various type of interferometric data sets.
- On-going wide application to various sources and other problems
 - Radio Stars, Protoplanetary disks, Jets
 - Faraday Tomography
- Next Scope: **3D/4D imaging**, Wide-field Imaging



Challenges for VLBI Imaging



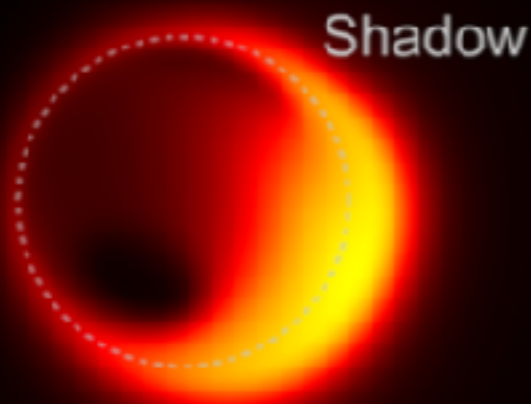
Sgr A* is scattered!

Diffractive scattering: invertible

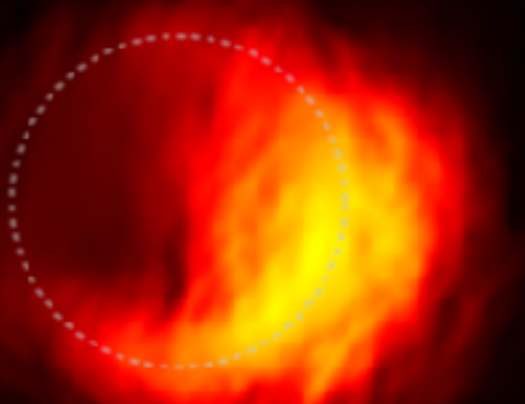
Refractive scattering: not invertible

Solution: regularize and solve the phase screen of the refractive scattering as well!

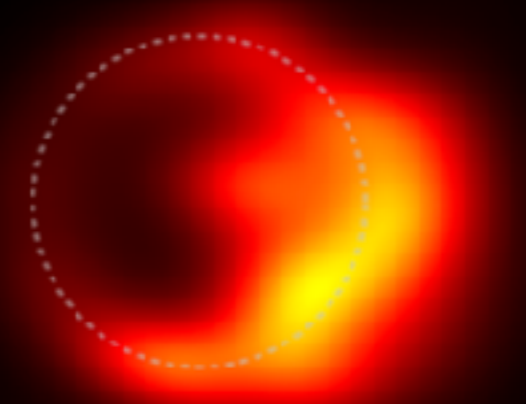
Unscattered



Scattered



Stochastic Optics Reconstructions

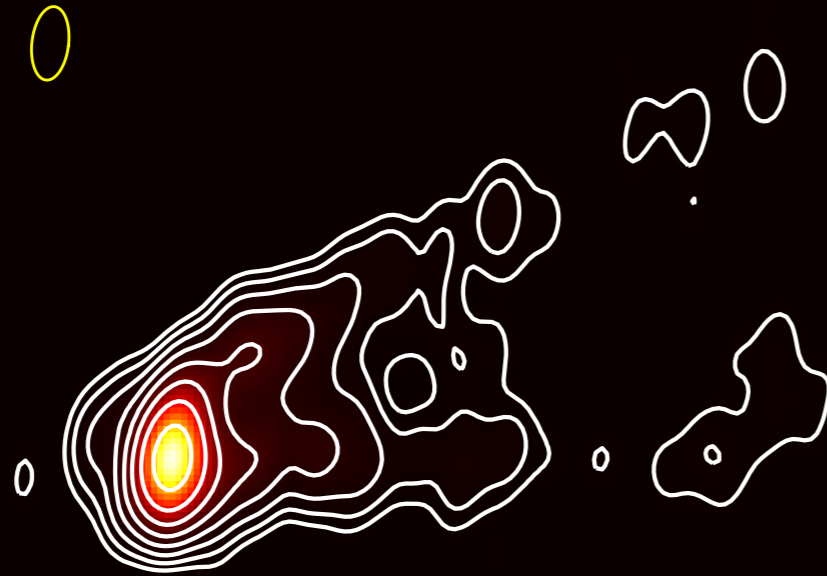


50 μ as

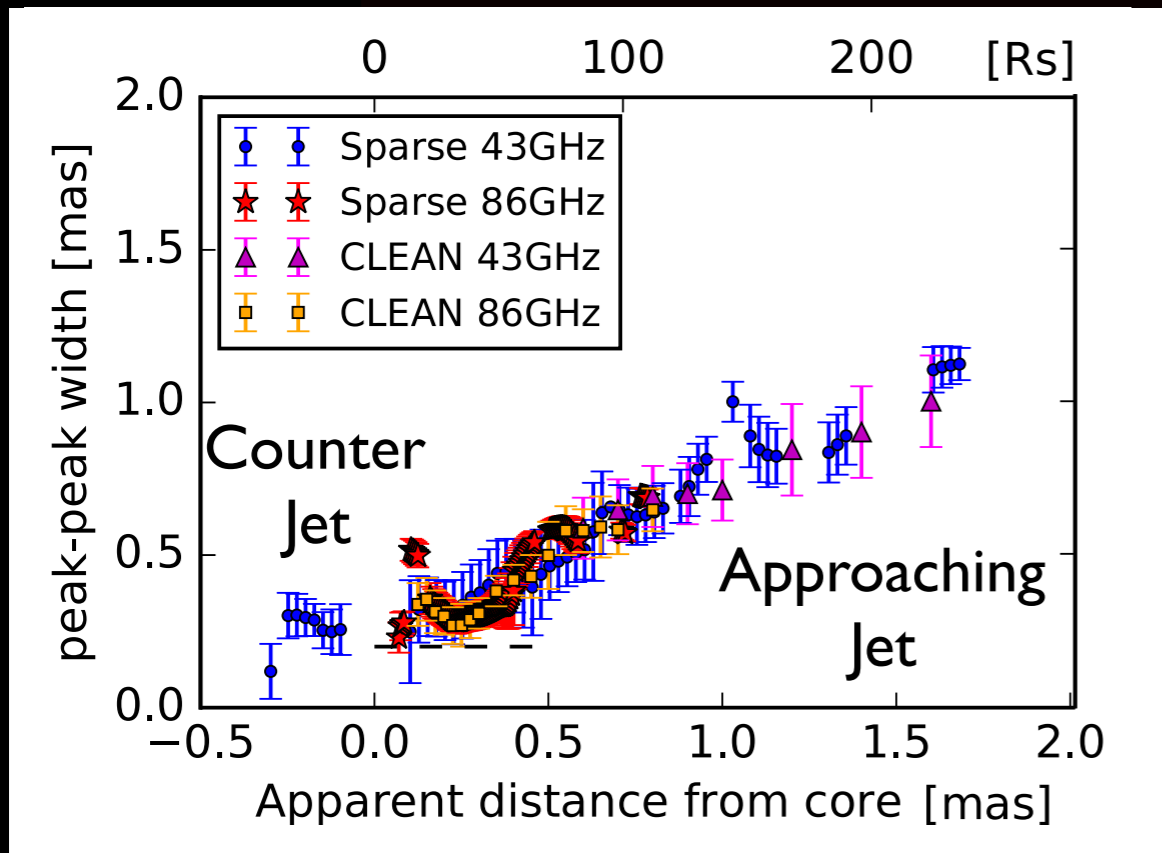
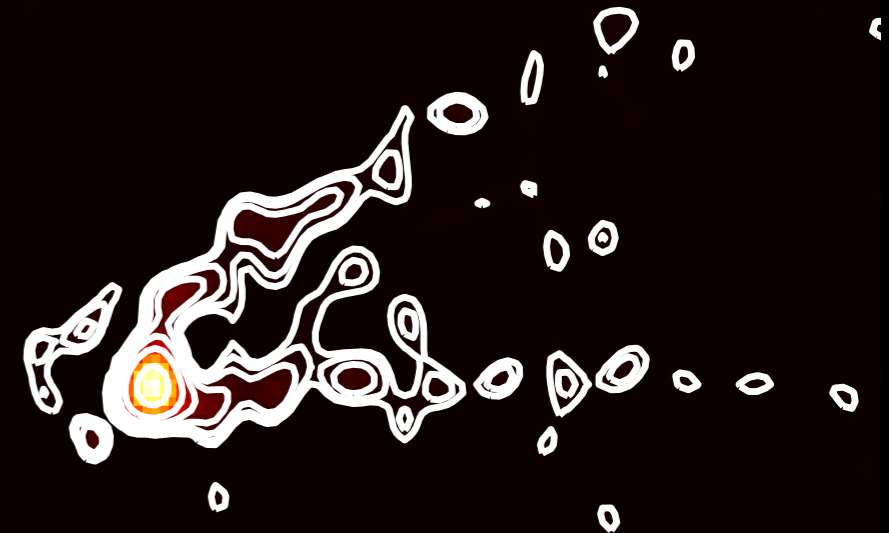
(Scattering Optics: Johnson 2016, ApJ)

Application to Real Data: VLBA M87 Data

CLEAN
(43 GHz)



Sparse
Modeling
(43 GHz)



Clear reproduction of counter jets

Derived collimation profile of the M87 jet is consistent with 86 GHz data

(Tazaki et al. 2017, submitted)

